

### XC Compute Performance Our solutions

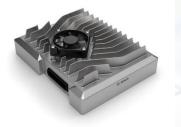
### COCKPIT INTEGRATION PLATFORM

Powerful control unit that integrates computing functions of the infotainment and instrumentation domains.



### ADAS INTEGRATION PLATFORM

High-performance central ADAS vehicle computer for driving and parking functions from NCAP up to L4.



## COCKPIT & ADAS INTEGRATION PLATFORM

Single highperformance computer that combines ADAS and cockpit functions in one ECU or even on one SoC.

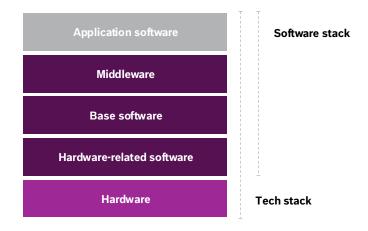




### Cockpit integration platform

### Host of infotainment and instrumentation software





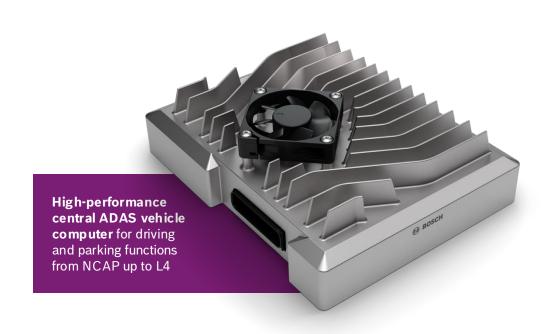


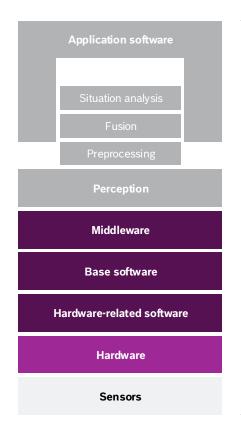


Software stack

# ADAS integration platform

### Host of driver assistance software





**←**)

Tech stack



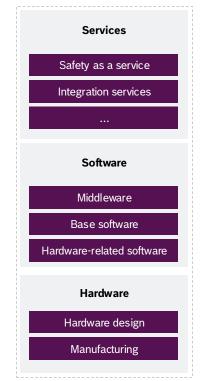


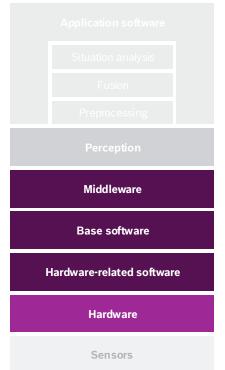
### ADAS integration platform

### Compute hardware, software, and services



#### ADAS integration platform





Software stack

Tech stack







### ADAS integration platform Flexible business models



Hardware+

Turnkey hardware device with base software and hardware-related software



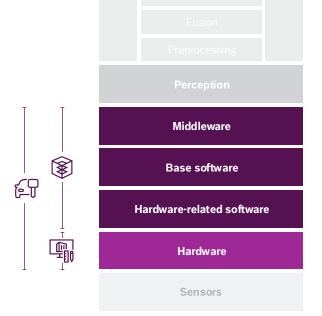
Integration services

Multilayer integration on Bosch or third-party hardware



Design services/ manufacturing

Hardware design with third-party manufacturing or manufacturing of customer or third-party design.



Software stack

Tech stack







# ADAS integration platform

## A safe and open integration platform

#### Hardware-only or turnkey solution

Enabled by broad ADAS system expertise incl. application software, middleware, and sensors



#### Multi SoC capability

Integration of multiple systems on chip (SoCs) protects the customer from SoC lock-in













#### Holistic vertical safety concept

Safety concept across the whole tech stack thanks to strong safety know-how



#### Scalable modular concept

Reusable building blocks allow flexible integration and scalability from cost-sensitive to high-performance segments





#### Open integration platform

Allows integration of customer-specific third-party software



#### Integration services

Integration on system, software, electronic control unit (ECU), and sensor level



#### Competitive perception

Powerful deep-learning algorithms for various ADAS sensors



#### Various business models

For hardware and non-hardware, e.g., hardware design, manufacturing, integration, or safety services, or hardware-related software (HSW)/basic software (BSW) only

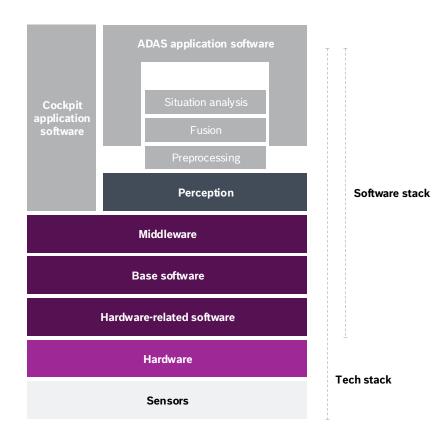






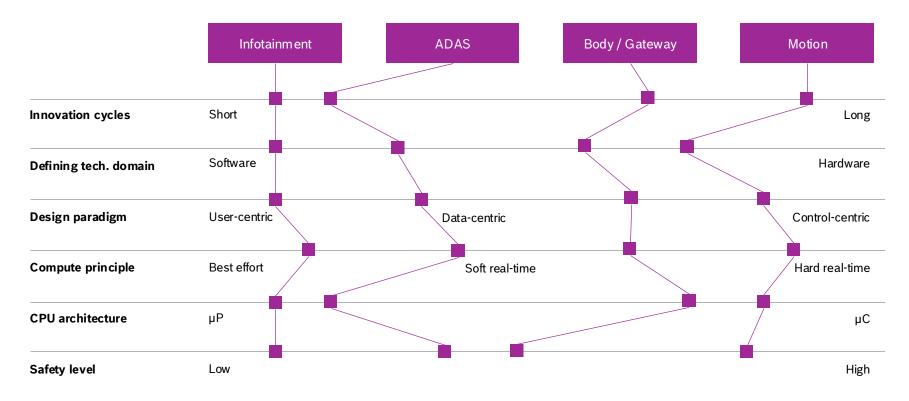
### Host of driver assistance software







### Domain fusion comparison



At the technology level, a fusion of infotainment and ADAS functions offers several advantages compared to an alternative fusion based on non-functional factors (schematically)







### Different architectural solutions for domain fusion

#### Trim level

(exemplary sensor set)

#### High (L2++/L3)

12× Video/Camera head, 5-7× Radar, 12× Ultrasonic sensor, 1× Lidar,

1x Occupant monitoring camera

#### Mid (L2+)

5× Video/Camera head, 5× Radar, 12x Ultrasonic sensor, 1x Occupant monitoring camera

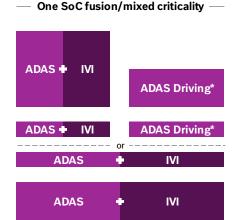
#### Entry (L0-L2)

2× Video/Camera head, 4× Radar, 12x Ultrasonic sensor, 1x Driver monitoring camera

### Standalone ECUs **ADAS** IVI **ADAS** IVI IVI **ADAS** Independent scalability between ADAS/IVI Low freedom from interference (FFI) complexity ■ Highest TCO and R&D costs Limited synergies on compute performance In development / series

### One ECU fusion **ADAS** IVI **ADAS** IVI Joint housing + cooling IVI ADAS Medium FFI complexity Medium cost reduction potential Re-use of existing ADAS/IVI stack ■ No passive cooling in entry segment Cost potential not fully utilized

In development





- Highest cost reduction potential
- Flexible compute resource allocation



- High FFI complexity
- Limited scalability on a single SoC

#### In-vehicle demonstrator available

\*Separation of ASIL-B and ASIL-D functions or driving and parking functions





### **Product overview**



### **Cockpit & ADAS** integration platform Multi domain fusion in a single ECU





Domain fusion of ADAS and cockpit functions in a single ECU or even on one SoC



TCO reduction of up to 30% possible whilst increasing efficiency in compute resource utilization



Scalability up to L3 through multi SoC fusion approach with different proven mechanical concepts

### Hardware-only or turnkey solution

Enabled by broad ADAS & cockpit system expertise incl. application software, middleware, and sensors

### Scalable modular concept from entry to high trim

Reusable building blocks allow flexible integration and scalability from cost-sensitive to highperformance segments including extension towards Gateway and Motion

#### Fusion compute platform benefits

### Cost saving potential on ECU and system-level

TCO reduction through less components, reduced R&D efforts. eased supplier handling and less logistics costs

### Flexibility for compute resource utilization

Dynamic loading for functions based on architecture, flexibility in usage of headroom for future feature additions

#### Multi SoC capability

Selection out of systems-on-chip (SoC) solutions from different vendors possible, e.g. Qualcomm or Renesas

Qualcom









